04.12.2018 – problem set n. 9

PRACTICAL PART

9.1. Lagrange interpolation. Let u be a continuous function on a planar domain $\Omega \subset \mathbb{R}^2$. Implement with the help of ALBERTA a program that plots the graph of the Lagrange interpolation $u_{\ell,\mathcal{M}}$ of u given by

 $\forall K \in \mathcal{M}$ $u_{\ell,\mathcal{M}|K} \in \mathbb{P}_{\ell}$ and $\forall z \in L_{\ell}(K)$ $u_{\ell,\mathcal{M}}(z) = u(z),$

where \mathcal{M} is an edge-to-edge triangulation of Ω and $L_{\ell}(K)$ denotes the principal Lagrange lattice of the simplex K.

For this purpose:

• Compute the vector of type DOF_REAL_VEC that contains the coefficients identifying $u_{\ell,\mathcal{M}}$ in the following manner: execute a non-recursive mesh traversal and, on any leaf, use the function

fe_space->bas_fcts->interpol(),

where FE_SPACE *fe_space denotes the global variable representing the finite element space $S^{\ell,0}(\mathcal{M})$.

• Plot with the function graphics().

Consider the partition \mathcal{M} of $\Omega =]0, 1[^2$ that is obtained by two refinements of any triangle in the macro triangulation which in turn is given by the two diagonals of Ω . Plot the Lagrange interpolation $u_{1,\mathcal{M}}$ of the function

$$u(x_1, x_2) = 1 - (x_1 - 0.4)^2 - (x_2 - 0.7)^2, \quad x = (x_1, x_2) \in [0, 1]^2.$$

Moreover, using the macro FOR_ALL_DOFS compute the largest coefficient of $u_{1,\mathcal{M}}$. Is this the maximum $u_{1,\mathcal{M}}$ in Ω ? Justify your answer.

THEORETICAL PART

9.2. Boundary and nodal values. Let \mathcal{M} be a simplicial mesh of a domain $\Omega \subset \mathbb{R}^d$, $\mathcal{P} = \{\mathbb{P}_{\ell}(K)\}_{K \in \mathcal{M}}$ with $\ell \in \mathbb{N}$ and write \mathcal{N} for the Lagrange nodes of \mathcal{M} . Verify the identity

$$\left\{ V \in \operatorname{FE}(\mathcal{M}, \mathcal{P}, C^{0}(\overline{\Omega})) \mid V_{\mid \partial \Omega} = 0 \right\}$$
$$= \left\{ V \in \operatorname{FE}(\mathcal{M}, \mathcal{P}, C^{0}(\overline{\Omega})) \mid \forall z \in \mathcal{N} \cap \partial \Omega \ V(z) = 0 \right\}.$$

Why is it useful?

9.3. Basis for continuous piecewise bilinear functions. Let \mathcal{M} be a mesh of a domain $\Omega \subset \mathbb{R}^2$ into rectangles, i.e. into sets of the type $R = [a_1, b_1] \times [a_2, b_2]$ with $a_1 < b_1$ and $a_2 < b_2$. Moreover, denote the set of vertices of \mathcal{M} by \mathcal{V} . Under suitable assumptions on \mathcal{M} , construct a basis of the type

$$\{\Phi_z\}_{z\in\mathcal{V}}$$
 such that $\forall y\in\mathcal{V} \ \Phi_z(y)=\delta_{yz}$

of the space

$$\{v \in C^0(\overline{\Omega}) \mid \forall R \in \mathcal{M} \ v_{|R} \in Q_1(R)\}$$

where

$$Q_1(R) = \{ q : R \to \mathbb{R} \mid \forall x = (x_1, x_2) \in R$$
$$q(x) = c_{00} + c_{10}x_1 + c_{01}x_2 + c_{11}x_1x_2 \}.$$

9.4. Point values and weak derivatives. Let $d \ge 2$. Show that the function

$$v(x) := \ln |\ln |x||, \quad x \in \Omega := \{x \in \mathbb{R}^d \mid |x| < \frac{1}{2}\}$$

verifies $v \in W^{1,p}(\Omega) \setminus L^{\infty}(\Omega)$ whenever $p \in [1, d]$. *Hint:* Write

$$\int_{\Omega} v \partial_i \varphi = \lim_{\epsilon \to 0} \int_{\Omega \setminus B_{\epsilon}(0)} v \partial_i \varphi$$

before integrating by parts.

9.5. First order Friedrichs inequality. Let $1 \leq p < \infty$ and $\Omega \subset \mathbb{R}^d$ be non-empty, open and bounded. Prove that, for all $v \in W_0^{s,p}(\Omega)$, we have

$$\|v\|_{0,p;\Omega} \le \operatorname{diam}(\Omega) |v|_{1,p;\Omega}$$

Hint: Prove the statement first for $v \in C_0^{\infty}(\Omega)$ and d = 1. Then exploit $\Omega \subset [a, b]^d$ for suitable $a, b \in \mathbb{R}$.

9.6. Weak Laplace operator. Let $\Omega \subset \mathbb{R}^d$ be a domain and endow $H_0^1(\Omega)$ with the norm

$$\cdot \mid_{1,2;\Omega} = \| \left| \nabla \cdot \right| \|_{0,2;\Omega},$$

which arises from the scalar product

$$H_0^1(\Omega) \ni (v, w) \mapsto \int_{\Omega} \nabla v \cdot \nabla w.$$

Given $v \in H_0^1(\Omega)$, define the (weak) Laplace of v by

$$\langle -\Delta v, \varphi \rangle := \int_{\Omega} \nabla v \cdot \nabla \varphi, \qquad \varphi \in H_0^1(\Omega).$$

Prove:

- (a) $-\Delta$ is a linear bounded operator from $H_0^1(\Omega)$ to $H^{-1}(\Omega)$.
- (b) The inverse of $-\Delta$ is the Riesz representation isometry of $H_0^1(\Omega)$.