Exam problems of Numerical methods for PDEs 1

year 2018/19 – valid until January 2020

1. One-dimensional convection-diffusion problems. Implement, in the programming language of your choice, a program to approximate one-dimensional boundary value problems of the form

$$-u'' + bu' = 0$$
 on $]0, 1[, u(0) = 1, u(1) = 0]$

with the help of linear and quadratic elements.

Determine the exact solution and apply your implementation, with global refinements reaching at least a maximum meshsize of 10^{-3} , to approximate it for b = 0.5, 5, 50, 500. Observe and comment the approximate solutions as well as their error decay in the (appropriately approximated) H^1 -error.

2. Investigating the quasi-optimality constant. Modify the source code ellipt.c in order to solve a problem of the form

$$-\operatorname{div}(A\nabla u) = f \text{ in } \Omega, \qquad u = g \text{ on } \partial\Omega,$$

where A is constant diagonal matrix, and to compute the so-called Riesz projection U^* into $S_g^{\ell,0}(\mathcal{M}) := \{v \in S^{\ell,0}(\mathcal{M}) \mid v = I_{\mathcal{M}}g\}$ given by

$$\forall \varphi \in S_0^{\ell,0}(\mathcal{M}) \quad \int_{\Omega} \nabla U^* \cdot \nabla \varphi = \int_{\Omega} \nabla u \cdot \nabla \varphi$$

and $I_{\mathcal{M}}$ denotes the Lagrange interpolation of order ℓ on the mesh \mathcal{M} .

Apply your implementation, with Lagrange elements of order $\ell \in \{1, 2, 3\}$ and global refinements, in order to approximate the exact solutions

$$u_1(x_1, x_2) = \sin(\pi x_1), \quad u_2(x_1, x_2) = \sin(\pi x_2),$$

 $u_3(x_1, x_2) = \sin(\pi x_1)\sin(\pi x_2)$

with

$$\Omega =]0, 1[^2, \quad A = \begin{pmatrix} \alpha & 0 \\ 0 & 1 \end{pmatrix}, \quad \alpha \in \{1, 10, 100\}.$$

Observe, compare, and comment the errors of the Galerkin approximation and the Riesz approximation in the H^1 -seminorm.

3. **Approximation of output functionals.** Consider the boundary value problem

$$-\Delta u = f \text{ in } \Omega, \qquad u = 0 \text{ on } \partial \Omega$$

and assume that we are interested in $\ell(u)$, where $\ell \in H^{-1}(\Omega)$ is a so-called output functional.

Implement, e.g. within ALBERTA, a program that computes $\ell(U)$ as an approximation for $\ell(u)$, assuming that ℓ is given as C function.

Use your implementation to determine the experimental order of convergence of $|\ell(U) - \ell(u)|$ in the following cases:

$$\Omega_1 = (-1, 1)^2, \quad u_1(x_1, x_2) = (x_1 + 1)(x_1 - 1)(x_2 + 1)(x_2 - 1),$$

$$\ell_1(v) = \frac{1}{4} \int_{\Omega_1} v,$$

$$\Omega_2 = \Omega_1 \setminus ((0, 1) \times (-1, 0)), \quad u_2(r, \varphi) = r^{2/3} \sin \frac{2\varphi}{3},$$

$$\ell_2 = \frac{1}{3} \int_{\Omega_2} v,$$

$$\Omega_3 = \Omega_1, \quad u_3 = u_1, \quad \ell_3(v) = v(0).$$

Compare and interpret the differences with the behavior of the errors $\|\nabla(u-U)\|_{0,2;\Omega}$, $\|u-U\|_{0,2;\Omega}$ as well as the available theoretical results.

INFORMATION:

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